

## SKILLS

*Rust, C/C++, Linux, Python, Git, KiCad, electronics test equipment, systems thinking*

## EDUCATION

University of California, Irvine

December 2025

*Master of Embedded and Cyber-Physical Systems*

Olin College of Engineering

May 2023

*Bachelor of Science, Electrical and Computer Engineering*

3.83 GPA

## EXPERIENCE

*Cybersecurity Research Intern* – Forescout Technologies

Summer 2023

- Created a toolkit of Python scripts that leverage large language models to generate decoy servers, files, and sensitive information in order to entice threat actors.

*Software Engineering Intern* – ThayerMahan

Summer 2022

- Created a prototype in Rust targeting embedded Linux that performs beam-steering analysis on streamed or recorded hydrophone sensor data and exports the results in JSON format.
- Researched and reported on the suitability of Rust for signal processing applications in the naval defense industry, highlighting cybersecurity, speed benchmarking, and ease of adoption.

*Systems Test Consultant* – Project WTR

Summer 2021

- Constructed a self-contained, auto-logging sensing suite with an Arduino and a Raspberry Pi to measure the multi-directional turning forces exerted on assistive walkers in order to compare their ease of use.
- Designed and performed maneuverability tests on a range of assistive walkers to determine market viability in advance of a patent application.

*Research Assistant* – Olin ThinSat

Spring 2021

- Designed a FreeRTOS satellite control program to launch a scientific payload within 40 miles of a ground observation site as part of orbital debris calibration experiments with Prof. Christopher Lee.
- Selected real-time clock, microcontroller, and EEPROM chip components considering accuracy, reliability, and suitability for use in satellite systems.

## PROJECTS

*Firmware/Power Electronics Engineer* – Senior Capstone

Fall 2022 - Spring 2023

- As part of a contracted project for Watts Water, designed an electrical system to extract power from a spinning turbine using regenerative braking techniques.
- Implemented firmware for a regenerative braking motor controller using an STM32 chip in Rust.
- Managed an \$8,000 budget to fulfill the material, equipment, and manufacturing needs of the five-person team across two prototype-revision cycles.

*Lead Systems Engineer* – Olin Rocketry

Fall 2021 - Spring 2022

- Core leadership in a team of 20 students designing the Phoenix IV, a high-powered model rocket that carried a 4 kilogram payload to 10,000 feet.
- Defined systems requirements matrix and power budget for Phoenix IV in alignment with NASA standard practices, and designed system integration testing plans to fulfill these requirements.